

Optical PLL for homodyne detection









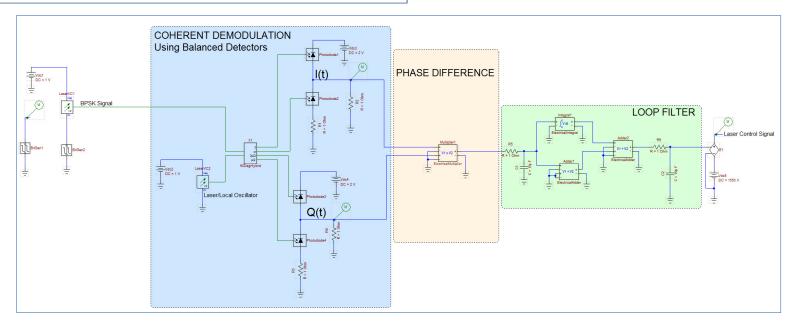




Optical BPSK PLL building blocks



- Signal Generation and Detection
 - BPSK Signal Generator
 - Local Oscillator
 - 90 degree hybrid
 - Balanced detectors
- Phase Difference Calculation
 - Electrical multiplier
- Feedback: Generating the control signal
 - Loop Filter
 - DC Offset













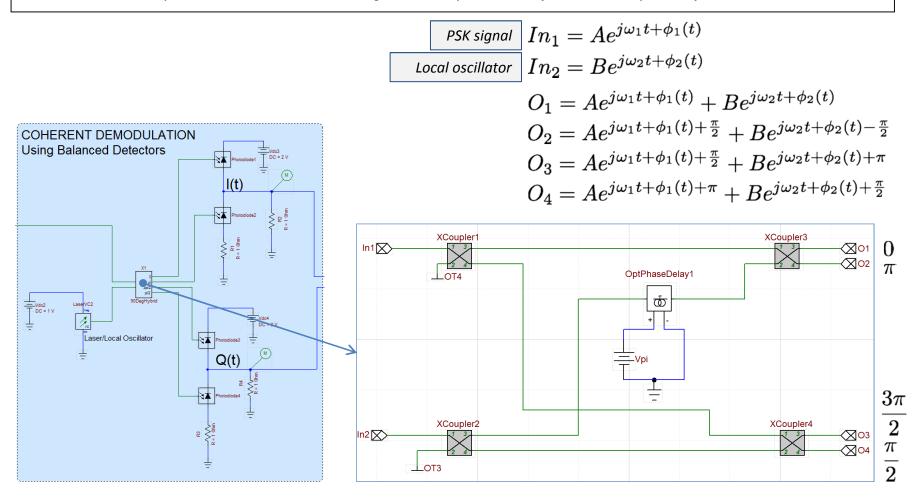




90 Degree Hybrid

The 90 Degree Hybrid mixes the incoming optical field with the local oscillator (LO) optical field and produces four outgoing signals with phase differences of 0, π , $3\pi/2$ and $\pi/2$

The electric field amplitudes of the PSK and LO signals are represented by A and B, respectively















Coherent detection with balanced detectors

The instantaneous power incident on each photodiode can be calculated as follows

$$P_t = \frac{1}{2} O_n O_n^*$$

Therefore the instantaneous field intensity (power) in each arm is equal to,

$$P_{t_1} = \frac{1}{2}(A^2 + B^2 + 2ABcos(\Delta))$$

$$P_{t_2} = \frac{1}{2}(A^2 + B^2 + 2ABcos(\Delta))$$

$$P_{t_3} = \frac{1}{2}(A^2 + B^2 + 2ABcos(\Delta + \frac{\pi}{2})) = \frac{1}{2}(A^2 + B^2 - 2ABcos(\Delta))$$

$$P_{t_4} = \frac{1}{2}(A^2 + B^2 + 2ABcos(\Delta + \frac{3\pi}{2})) = \frac{1}{2}(A^2 + B^2 + 2ABsin(\Delta))$$

$$P_{t_4} = \frac{1}{2}(A^2 + B^2 + 2ABcos(\Delta + \frac{\pi}{2})) = \frac{1}{2}(A^2 + B^2 - 2ABsin(\Delta))$$

$$\Delta = \omega_1 t - \omega_2 t + \phi_1(t) - \phi_2(t)$$







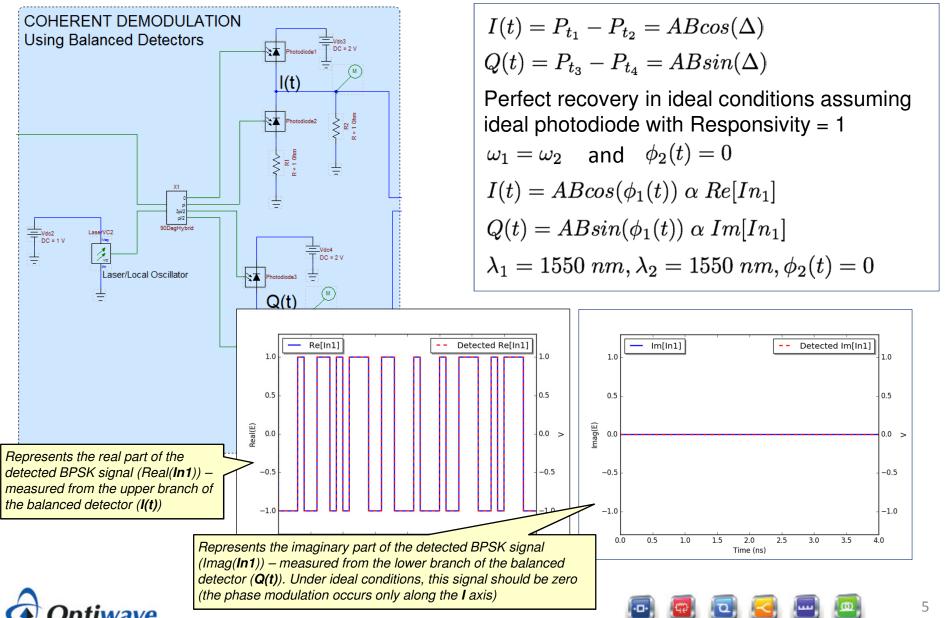








Homodyne balanced detection (ideal)













Homodyne balanced detection (non-ideal)

In non-ideal conditions phase correction is needed

$$\omega 1 \neq \omega_2$$
 and/or $\phi_2(t) \neq 0$

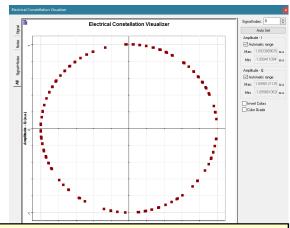
$$I(t) = AB\cos(\phi_1(t) + \Delta\phi(t))$$

$$Q(t) = ABsin(\phi_1(t) + \Delta\phi(t))$$

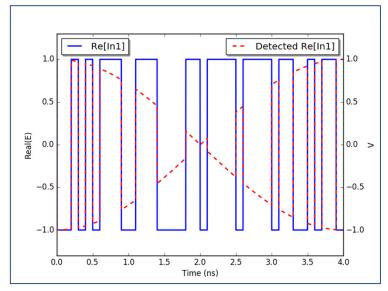
$$\Delta\phi(t) = \omega_1 t - \omega_2 t - \phi_2(t)$$

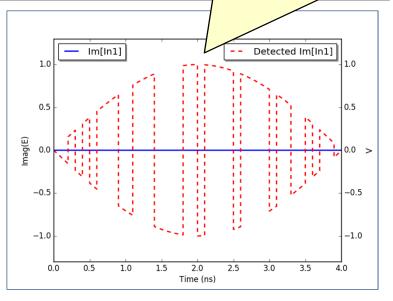
Rotation in the constellation diagram

$$\lambda_1 = 1550 \ nm, \lambda_2 = 1550.001 \ nm, \phi_2(t) = 0$$



Due to a frequency difference between the signal and LO, the detected BPSK signal constellation will have terms in both the I (real) and Q (imaginary) axes. This results in a rotation of the I-Q constellation

















Phase difference (Electrical multiplier) 1

Electrical multiplier estimates the phase by multiplying I and Q

$$I(t) * Q(t) = (AB)^2 cos(\phi_1(t)) sin(\phi_1(t))$$

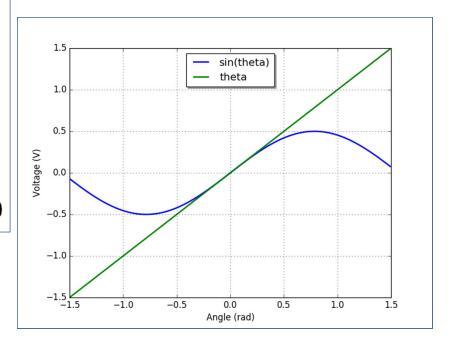
$$I(t)*Q(t) = \frac{(AB)^2}{2}sin(2\phi_1(t))$$

Using small angle approximation $sin(\theta) \approx \theta$

$$I(t) * Q(t) \approx (AB)^2 \phi_1(t)$$

The plot shows the sweep of the phase where

$$\lambda_1 = 1550 \; nm, \lambda_2 = 1550 \; nm, \phi_1 = -\pi \; to \; \pi, \phi_2 = 0$$















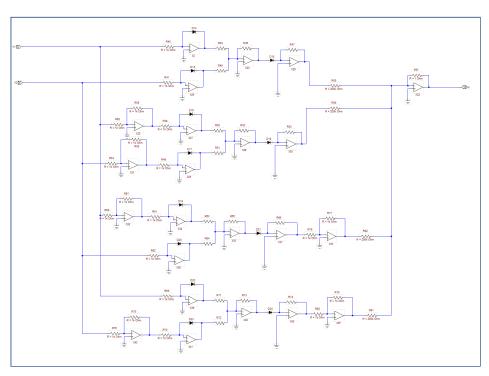


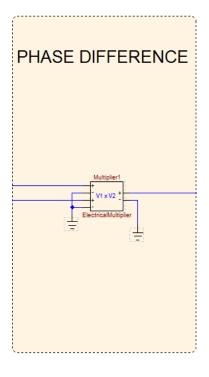
Phase difference (Electrical multiplier) 2

There is no straightforward circuit for analog multiplication (normally achieved by using log and inverse log)

$$AB = log^{-1}(log(A) + log(B))$$

This can be realized using operational amplifiers or transistors (see left diagram below). OptiSPICE also has an electrical multiplier element (see right diagram below) which can perform this operation <u>mathematically</u>.

















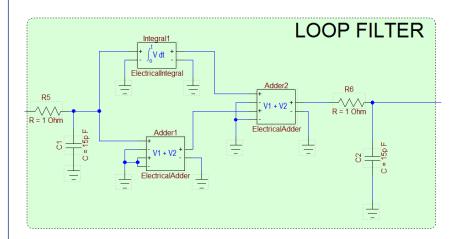
Loop Filter-PI Controller

A loop filter is used to generate the control signal for the tunable laser from the detected phase difference. It consists of a proportional integral controller and a low pass filter

$$V_{cont} = K_I \int \phi dt + K_p \phi$$

 $K_I \& K_p$ are scaling factors

 ϕ is the output of the electrical multiplier which is the detected phase difference (error signal)



- Adder and Integrator circuits can be created using operational amplifiers
- OptiSPICE has built-in voltage <u>adder</u> and <u>integrator</u> elements that can be used directly to perform these operations
- The controller works as long as the phase or frequency difference is not too large
- There is not any straight forward way to figure out the values for the scaling factors
- They can be adjusted manually or through an optimization routine to obtain a desired PLL response









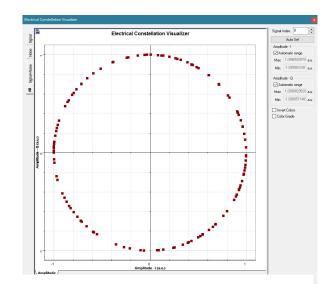




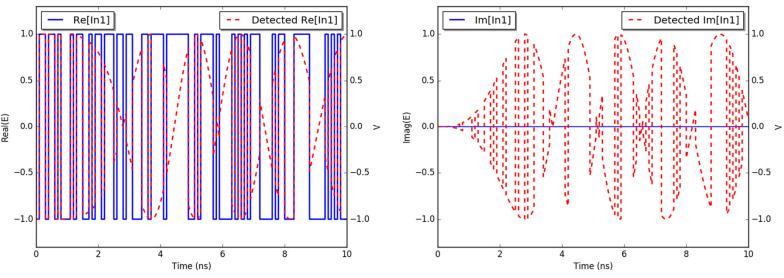
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Simulation results – no PLL

Without the active phase correction of the PLL a constant frequency difference between the local oscillator and the carrier signal detected I and Q do not have the correct phase (pi or –pi for BPSK). The constant frequency difference results in the rotation of the constellation diagram



Phase Locked Loop OFF









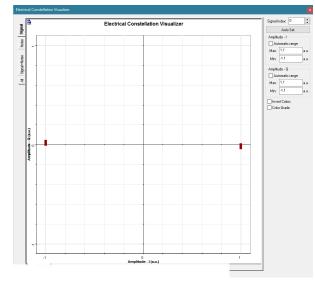






Simulation results - PLL on

When the PLL is activated the frequency/phase of the local oscillator tracks the frequency/phase of the carrier signal. Therefore the detected I and Q have the right phase and the constellation diagram does not rotate



Phase Locked Loop ON

